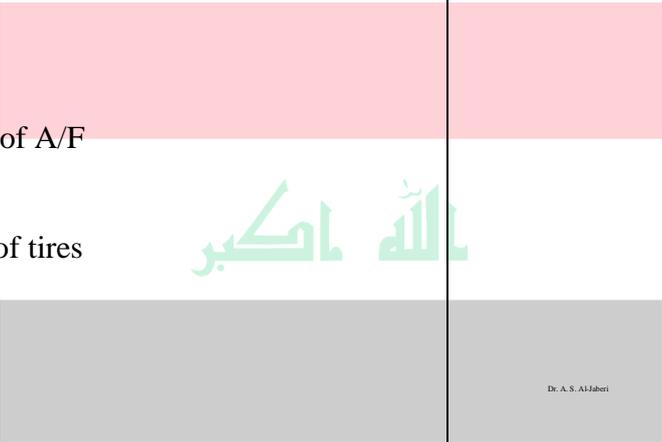


<b>Subject Number: ANTE 436</b> <b>Subject: Designs of Aircraft</b> <b>Units: 7</b> <b>Weekly Hours: Theoretical: 3</b> <b>Experimental: 1</b> <b>Tutorial :</b>	
Week	Contents
1	<b>Introduction</b> - Design and development of aircraft - Design stages - Preliminary design department
2	<b>Airworthiness</b> - Definition - BCAR - FAR - Crash airworthiness
3	<b>Fuselage design</b> - Main characteristics - Fuselage design requirements - Shape of fuselage
4	- Cabin cross section layouts - Cabin cross-section dimensions - Cabin length - Cockpit
5	- Fuselage main dimensions Quick method General method - Fuselage weight
6	<b>Wing design</b> - Basic requirements - Wing location - Wing geometric characteristics - Evaluation of wing size
7	- Evaluation of SMC - Evaluation of MAC - Analytical method - Graphical method - Diagrammatical method
8	- Airfoils, requirements & definitions - Airfoils coding - High lift devices - Wing aerodynamic characteristics
9	- Lift coefficient increment due to T.E. flaps Split flaps Single slotted flaps Double slotted flaps - Wing weight

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<p><b>10</b></p> <p><b>11</b></p>	<p><b>Empennage design</b></p> <ul style="list-style-type: none"> <li>- Tail surfaces functions</li> <li>- Types of surface control system</li> <li>- Tail surface configuration</li> <li>- Horizontal tail plane</li> <li>- Vertical tail plane</li> <li>- Empennage weight</li> </ul>
<p><b>12</b></p> <p><b>13</b></p> <p><b>14</b></p>	<p><b>Under-carriage design</b></p> <ul style="list-style-type: none"> <li>- General requirements</li> <li>- Runways classification</li> <li>- Types of undercarriage</li> <li>- Tailoring u.c. to bearing capacity of A/F</li> <li>- LCN For single wheel</li> <li>- LCN For two or more wheels</li> <li>- Type, size and inflation pressure of tires</li> <li>- Shock absorption. Leg length</li> <li>- Ground load factor</li> <li>- Ground load cases</li> <li>- Structural load cases</li> <li>- Weight of u.c</li> </ul>
<p><b>15</b></p> <p><b>16</b></p>	<p><b>Preliminary weight analysis</b></p> <ul style="list-style-type: none"> <li>- Weight break down</li> <li>- Surface controls group</li> <li>- Engine section or nacelle group</li> <li>- Propulsion group. Engine weight (dry)</li> <li>- Airframe services and equipments</li> <li>- Operational loads</li> <li>- Crew weight</li> <li>- Payload</li> <li>- Fuel weight (based on flight stages)</li> <li>- Fuel weight (based on aircraft type) ( calculation by using graphics)</li> </ul>
<p><b>17</b></p>	<p><b>Choice of engines</b></p> <ul style="list-style-type: none"> <li>- Take off stages</li> <li>- Computing of static thrust</li> <li>- Computing minimum required thrust</li> </ul>
<p><b>18</b></p> <p><b>19</b></p>	<p><b>Center of gravity</b></p> <ul style="list-style-type: none"> <li>- Evaluation of aircraft center of gravity</li> <li>- Loading and balancing diagram</li> <li>- Wing location according to aircraft center of gravity</li> </ul>
<p><b>20</b></p>	<p><b>Payload-range diagram</b></p> <ul style="list-style-type: none"> <li>- Limiting weight definitions</li> <li>- For turbo-jet aircraft</li> <li>- For turbo-prop aircraft</li> </ul>



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21	<b>Flight and gust envelope</b> - Load factor - Load factor at steady pullout - Load factor at correctly banked turn - Flight envelope
22	- Gust envelope - Flight - gust envelope
23	<b>Wing and tail loads (for flight-gust envelope)</b> - Aircraft pitching moment of inertia - Load calculation at level flight with angular acceleration
24	<b>Span wise air and inertia load distribution</b> - Air load distribution Schrenk method
25	- Air load distribution Diederich method
26	- Wing group inertia load distribution - Fuselage group inertia load distribution
27	<b>Drag estimation</b> - Area drag method: Wing Empennage Fuselage
28	- Area drag method: Cockpit Undercarriage Nacelle Wing/fuselage interference
29	- Empirical method for cruising stage - Induced drag coefficient of wing with part-span flap
30	<b>Structural design</b> - Aircraft main part structural design

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<b>Subject Number: ANTE 435</b>	
<b>Subject: Aircraft Propulsion Systems Technology and Design</b>	
<b>Units: 5</b>	
<b>Weekly Hours: Theoretical: 2</b>	
<b>Experimental: 1</b>	
<b>Tutorial : 1</b>	
<b>Week</b>	<b>Contents</b>
<b>1</b>	<b>Introduction</b> - Classification of propulsion systems - The thrust equation
<b>2</b>	<b>Engine performance</b> - Engine performance and A/C range
<b>3</b>	<b>Theory of jet propulsion</b> - Turbo jet engine - Turbo fan engine - Turbo prop engine - Turbo shaft engine - Ram jet engine
<b>4</b>	
<b>5</b>	
<b>6</b>	<b>Design of centrifugal compressors</b> - Impeller design - Diffuser design - Volute design
<b>7</b>	
<b>8</b>	<b>Design of axial flow compressors</b> - Compressor aerodynamics - Repeating stage , repeating row - Mean line design - Axial variation - Radial variation - Mechanical design
<b>9</b>	
<b>10</b>	
<b>11</b>	
<b>12</b>	<b>Design of combustion system</b> - The process (ignition, stability, length scaling, diffusers) - After burner design - Flame holding - Fuel injection
<b>13</b>	
<b>14</b>	<b>Combustion chambers technology</b> - Materials - Manufacturing technology
<b>15</b>	<b>Design of axial flow turbines</b> - Turbine aerodynamics - Zero exit swirl, constant axial velocity

16	<ul style="list-style-type: none"> <li>- Mean line stage design</li> <li>- Other design considerations</li> </ul>
17	<b>Mechanical design of axial flow turbines</b> <ul style="list-style-type: none"> <li>- Rotor airfoil centrifugal stresses</li> <li>- Rim web thickness</li> </ul>
18	
19	<b>Turbines technology</b> <ul style="list-style-type: none"> <li>- Materials</li> <li>- Manufacturing technology</li> <li>- Balancing</li> </ul>
20	<b>Design of inlets</b> <ul style="list-style-type: none"> <li>- Subsonic inlets</li> <li>- Supersonic inlets</li> </ul>
21	<b>Design of nozzles</b> <ul style="list-style-type: none"> <li>- Convergent nozzle</li> <li>- Convergent- divergent nozzle</li> <li>- Thrust reversing and thrust vectoring</li> <li>- Nozzle coefficients</li> </ul>
22	
23	<b>Inlets and nozzles technology</b> <ul style="list-style-type: none"> <li>- Materials</li> <li>- Manufacturing technology</li> </ul>
24	<b>Accessory drives</b> <ul style="list-style-type: none"> <li>- Construction of gearboxes and drives</li> <li>- Engine power off takes</li> <li>- Engine oil system</li> </ul>
25	<b>Engine control systems</b> <ul style="list-style-type: none"> <li>- Engine/Airframe interfaces</li> <li>- Control systems</li> </ul>
26	<b>Engine starting</b> <ul style="list-style-type: none"> <li>- Fuel/Ignition control</li> <li>- Engine rotation</li> <li>- Throttle levers</li> <li>- Starting sequence</li> </ul>
27	<b>Turbine engine inspection and maintenance</b> <ul style="list-style-type: none"> <li>- Inlet and compressor section</li> <li>- Combustion section</li> <li>- Turbine section</li> <li>- Exhaust section</li> </ul>
28	
29	
30	

<b>Subject Number: ANTE 438</b> <b>Subject: Aircraft Stability and Control</b> <b>Units: 5</b> <b>Weekly Hours: Theoretical: 2</b> <b>Experimental: 1</b> <b>Tutorial : 1</b>	
Week	Contents
1	<b>Introduction to A/C stability and control</b> - The freedom of motion of aircraft - Basic axis
2	<b>Aircraft longitudinal static stability</b> - Definition of longitudinal static stability and conditions - General equation
3	<b>Aircraft pitching moment</b> - Pitching moment coefficient as a function of angle of attack - trimmed conditions
4	<b>Applications</b> - Examples
5	<b>Directional static stability</b> - General equations - Conditions of stability
6	<b>The longitudinal equations of motion- A rigid symmetric A/C</b> - Derivation of longitudinal equations of motion
7	<b>Applications</b> - Examples
8	<b>Longitudinal stability derivatives</b> - All the longitudinal stability derivatives equations
9	<b>Equations of motion as a function of stability derivatives</b> - Derivation of longitudinal equations of motion in terms of the stability derivatives
10	<b>Applications</b> - Examples
11	<b>Longitudinal equations of motion solution</b> - Response to elevator as a function of input signal
12	<b>A/C characteristic equation</b> - Solution of characteristic equation - Types of period oscillation

13	<b>Derivation of lateral directional equations of motion and solution</b> <ul style="list-style-type: none"> <li>- Derivation of lateral directional equations of motion in terms of the stability derivatives</li> <li>- The solution</li> </ul>
14	<b>Applications</b> <ul style="list-style-type: none"> <li>- Examples</li> </ul>
15	<b>Yaw damper from stability and control augmentation</b> <ul style="list-style-type: none"> <li>- Principles of yaw damper</li> <li>- General equations</li> <li>- Effect of yaw damper on stability and control of A/C</li> </ul>
16	<b>Introduction to non linear dynamics</b> <ul style="list-style-type: none"> <li>- General introduction</li> <li>- Stall dynamic</li> <li>- Wing rock</li> </ul>
17	<b>Applications</b> <ul style="list-style-type: none"> <li>- Examples</li> </ul>
18	<b>Gust equations derivation and its applications</b> <ul style="list-style-type: none"> <li>- Load factor estimation from the gust</li> <li>- Types of gust</li> <li>- Effect on response</li> </ul>
19	<b>Longitudinal autopilot</b> <ul style="list-style-type: none"> <li>- Longitudinal equations of autopilot</li> </ul>
20	<b>Pitch orientation control system</b> <ul style="list-style-type: none"> <li>- Deriving basic equations of pitch orientation control system</li> </ul>
21	<b>Flight path stabilization</b> <ul style="list-style-type: none"> <li>- Mach hold</li> <li>- Altitude hold</li> </ul>
22	<b>Vertical gyro as the basic attitude reference</b> <ul style="list-style-type: none"> <li>- Main idea of the gyro as the indicator of angle</li> </ul>
23	<b>Lateral autopilot</b> <ul style="list-style-type: none"> <li>- Main assumptions</li> </ul>
24	<b>Damping of Dutch roll</b> <ul style="list-style-type: none"> <li>- The principle of Dutch roll damping</li> </ul>
25	<b>Yaw orientation control system</b> <ul style="list-style-type: none"> <li>- Derivation of the main equations</li> </ul>
26	<b>Other lateral autopilot configuration</b> <ul style="list-style-type: none"> <li>- Introduction and principles</li> </ul>
27	<b>Lateral transfer function for rudder displacement</b> <ul style="list-style-type: none"> <li>- Deriving the transfer function of basic rudder equation of motion</li> </ul>

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28	<b>Lateral transfer function for ailerons</b> - Deriving the transfer function of ailerons displacement
29	<b>Lateral transient response for A/C</b> - Explanation and the calculation methods of transient response
30	<b>Applications</b> - Examples

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<b>Subject Number: ANTE 434</b> <b>Subject: Aircraft Structures</b> <b>Units: 5</b> <b>Weekly Hours: Theoretical: 2</b> <b>Experimental: 1</b> <b>Tutorial : 1</b>	
Week	Contents
1	<b>Introduction</b> - General viewing
2	<b>Structure components</b> - Skin, Spar, Stiffeners and stringers - Rib, Frame (Ring) - Monocoque, Semi-monocoque - Definitions - Elastic axis, Shear center
3	<b>Aircraft construction materials</b> - Wood - Aluminum alloys - Magnesium alloys - Steel alloys - Titanium alloys - Plastics - Glass - Composite materials
4	
5	<b>Wing cross section structure</b> - Simple box beam - Simple nose - Center box - Multi- flanges cell - Multi-cells - Multi-cells multi flanges
6	<b>Bending of open and closed section beams</b> - Introduction - Sign conventions and notations - Resolution of bending moments - Direct stress distribution due to bending - Load intensity, shear force and bending moment relationships - Deflection due to bending - Approximations for thin-walled sections
7	
8	
9	
10	<b>General stress, strain and displacement relationships</b> - For open and single cell closed section thin walled beams

11	<b>Shear stress</b>
12	- Shear of thin-walled open tubes, without booms
13	- Shear of thin-walled closed sections beams, without booms - Twist and warping of closed section beams - Shear center
14	<b>Pure torsion</b> - Torsion of open section beams - Bredth-Batho formula - Torsion of closed section beams
15	<b>Analysis of combined open and closed sections</b> - Bending - Shear - Torsion
16	<b>Structural idealization</b> - Idealization of open and closed beam sections
17	<b>Effect of idealization</b> - Bending, shear and torsion of open and closed section beams
18	<b>Deflection</b> - Deflection of open and closed section beams
19	<b>Span-wise taper effect</b> - Single web beam. - Open and closed sections - Beams having variable string areas
20	<b>Fuselage</b> - Bending - Shear - Torsion
21	- Fuselage frame analysis - Cut-outs in fuselage
22	<b>Wing</b>
23	- Bending
24	- Torsion - Shear - Shear center
25	- Taper effect - Method of successive approximation/ Torsion
26	- Method of successive approximation/ Shear - Deflection
27	- Wing ribs analysis
28	- Cut-outs in wings

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29	<b>Fatigue</b> - Safe life and fail-safe design - Fatigue strength of components
30	- Goodman method - Miner & Palmgren method - s-n curve - Prediction of aircraft fatigue life

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**Subject Number: ANTE 439**  
**Subject: Aircraft Systems and Maintenance**  
**Units: 6**  
**Weekly Hours: Theoretical: 2**  
**Experimental: 2**  
**Tutorial :**

Week	Contents
1	<b>Aircraft systems</b> - Introduction - Basic definitions
2	<b>Basic components used in aircraft mechanical systems</b> - Aircraft hardware - Pumps - Valves and pipes - Filters and cocks
3 4 5	<b>Fuel system</b> - Fuel system components - Fuel system operating modes - Integrated civil aircraft systems - Troubleshooting - Maintenance
6 7 8	<b>Hydraulic system</b> - Hydraulic system components - Types of hydraulic systems used in the modern aircrafts - Troubleshooting - Maintenance
9 10	<b>Pneumatic system</b> - Pneumatic system components - Troubleshooting - Maintenance
11 12 13 14	<b>Environmental control systems</b> - The need for a controlled environment - Environmental control system design - Cooling systems - Air distribution system - Air conditioning system - Oxygen system - cabin pressurization - De-ice systems - Troubleshooting - Maintenance
15	<b>Emergency systems</b> - Warning systems - Fire detection and suppression

	<ul style="list-style-type: none"> <li>- Emergency power sources</li> <li>- Emergency oxygen</li> <li>- Emergency systems maintenance</li> </ul>
16	<b>Flight control systems</b> <ul style="list-style-type: none"> <li>- Flight control surfaces</li> <li>- Flight control linkage systems</li> </ul>
17	<ul style="list-style-type: none"> <li>- High lift control systems</li> <li>- Trim and feel</li> </ul>
18	<ul style="list-style-type: none"> <li>- Flight control actuation</li> <li>- Fly-By-Wire control laws</li> <li>- Troubleshooting</li> <li>- Maintenance</li> </ul>
19	<b>Landing gear systems</b> <ul style="list-style-type: none"> <li>- Construction</li> <li>- Landing gear system maintenance</li> <li>- Inspection and maintenance of brake system and Tires</li> </ul>
20	<b>Airframe</b> <ul style="list-style-type: none"> <li>- Inspection</li> <li>- Maintenance</li> </ul>
21	<b>Inspection fundamentals</b> <ul style="list-style-type: none"> <li>- General</li> </ul>
22	<ul style="list-style-type: none"> <li>- Required inspections</li> </ul>
23	<ul style="list-style-type: none"> <li>- CHECKLIST</li> </ul>
24	<ul style="list-style-type: none"> <li>- Aircraft Logs</li> <li>- Special inspections</li> </ul>
25	<ul style="list-style-type: none"> <li>- Publications Bulletins Maintenance manual</li> <li>Overall manual</li> <li>Structural repair manual</li> <li>Parts catalog</li> <li>- Federal Aviation Regulation (FAR)</li> <li>- Airworthiness directives</li> <li>- Type certificate data sheets</li> </ul>
26	<b>Ground handling and support equipments</b> <ul style="list-style-type: none"> <li>- General</li> <li>- Starting engines</li> <li>- Power units</li> </ul>
27	<ul style="list-style-type: none"> <li>- Air conditioning and heating units</li> <li>- Ground support air start units</li> <li>- Preoiling equipment</li> <li>- Aircraft fueling</li> </ul>
28	<ul style="list-style-type: none"> <li>- Servicing aircraft with oil</li> <li>- Aircraft Tiedown</li> <li>- Movement of aircraft</li> <li>- Maintenance safety</li> </ul>

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29	CAA License
30	- Qualifications structure - EASA66/JAR66 syllabus modules and applicability - Examinations and levels

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<b>Subject Number: CREQ 449</b> <b>Subject: Computer Added Engineering</b> <b>Units: 2</b> <b>Weekly Hours: Theoretical:</b> <b>                          Experimental: 3</b> <b>                          Tutorial :</b>	
Week	Contents
1	<b>Introduction to CAE</b> - Characteristics of CAE and its importance
2	<b>Introduction to Modeling</b> - Dealing with real physical objects - Treating them as CAE models
3	<b>Modeling of 3-Dimensional Problems</b> - Some examples of solid objects of real problems
4	- Loads & boundary conditions - Utilization of symmetry to simplify problems modeling
5	<b>Reduction to Plane Problems</b> - Importance & conditions of reduction to plane problems
6	- Reduction to axi- symmetrical models
7	- Modeling 2-D plane stress, plane strain, and fluid flow
8	<b>Bar, Beam, Problems</b> - Analysis of bar, beam problems
9	<b>Plate Problems</b> - Condition of reduction to plate model - Load, Symmetry
10	<b>Meshing; 2-D</b> - Types of mesh - Methods of meshing
11	<b>Meshing 3-D</b> - Types of mesh - Methods of meshing
12	<b>Meshing Bar, Beam, and Plate</b> - Types of mesh - Methods of meshing
13	<b>Load – Structural</b> - Types & implementation of structural loads
14	<b>Load – Thermal</b> -Types & implementation of thermal loads

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15	<b>Load – Fluid</b> - Types & implementation of fluid- flow loads
16	<b>Solution- Structural</b> - Static structural problems
17	<b>Solution – Dynamic</b> - Dynamic structural problems
18	<b>Solution – Thermal</b> - Heat transfer problems
19	<b>Solution- Fluid</b> - Fluid flow problems
20	<b>Results</b> - Types of results - Visual contours & data results
21	- Results at internal sections - Animation
22	<b>Report Generation</b> - Software- dependent generation of eng. Reports of analyzed problems
23	<b>Applications</b> - Static 3D stress analysis problem
24	- Steady- state heat transfer problem
25	- Laminar flow problem
26	- Modal analysis problem
27	<b>Importing Geometry</b> - Types & standards of solid geometry - Importing from CAD systems
28	<b>Contact Problems</b> - Introduction to contact problems - Software- specific implementation
29	<b>Plastic Deformation</b> - Non-linear material behavior and solution
30	<b>Phase- change problems</b> - Analysis & implementation of phase- change problems

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<b>Subject Number: ANTE 418</b> <b>Subject: Automatic Control</b> <b>Units: 5</b> <b>Weekly Hours: Theoretical: 2</b> <b>Experimental: 1</b> <b>Tutorial : 1</b>	
Week	Contents
1	<b>Introduction and definitions</b> - Basic definitions about the concepts of control
2	<b>Mechanical system and Transfer Function</b> - Definition of transfer function - Deriving the transfer function for three basic parts of mechanical system
3	<b>Series and parallel connections in mechanical systems</b> - Transfer function for mechanical system while connected it at series and parallel - Examples
4	<b>Torsional system</b> - Deriving the transfer function for three basic parts of torsional System
5	<b>Electrical system, series and parallel connections</b> - Deriving the transfer function for three basic parts of electrical system connected in parallel and series
6	<b>Thermal and fluid systems</b> - Deriving the transfer function for thermal and fluid systems - Examples
7	<b>Hydraulic system</b> - The basic concept of working the hydraulic system - Deriving the transfer function of the system
8	<b>Hydraulic servomotor system</b> - Leverage system and deriving the transfer function for three cases of fixing - Method of connection with hydraulic system

9	<b>Pneumatic system</b> - The basic concept of working the pneumatic system - Deriving the transfer function of the system
10	<b>Block diagram</b> - The principles of block diagram - The basic nine rules for reduction the block diagram
11	<b>Block diagram reduction</b> - Method of reduction of block diagrams of multi-input and output
12	<b>Types of control and Laplace transformations</b> - Types of control methods and basic functions of Laplace transformation
13	<b>Test signals</b> - The different types of test signals
14	<b>Response of first order system</b> - Method of computing the response of first order system - Examples
15	<b>Response of second order system</b> - Method of computing the response of second order system - Examples
16	<b>Response specifications</b> - The specification of response which determine the stability of system
17	<b>Steady state error</b> - Computing the steady state error by using Toyler method and normal method and compare between them
18	<b>Response improvement</b> - The methods of response improvement - Examples
19	<b>System stability</b> - The concept of system stability and its effect on control process
20	<b>Routh criterion</b> - The Routh criterion for computing the stability of system
21	<b>Applications of Routh criterion</b> - Some applications about Routh criterion - Examples
22	<b>Root-locus method</b> - The root-locus method for computing system stability

23	<b>Rules of Root-locus method</b> - Basic rules of root-locus method - Examples
24	<b>Polar-plot diagrams</b> - The polar plot for computing system stability
25	<b>Principles of polar-plot diagrams</b> - The method of polar plot diagram for computing the gain - Examples
26	<b>Logarithmic Scales and Bode Plots</b> - Basic principles of logarithmic scale and Bode plots
27	<b>Construction of Bode Plots for Continuous-Time Systems</b> - The method of construction of Bode plots - Examples
28	<b>Analysis of control system in state space</b> - Principles and basic assumptions for state space method
29	<b>State space representation of transfer function of system</b> - The state space representation - Examples
30	<b>Solving the time invariant state equations</b> - The solution method of time invariant state equations

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<b>Subject Number: ANTE 437</b> <b>Subject: Aircraft Vibration</b> <b>Units: 6</b> <b>Weekly Hours: Theoretical: 2</b> <b>Experimental: 2</b> <b>Tutorial :</b>	
Week	Contents
1	<b>Introduction</b> - Basic concepts of vibration and applications - Calculation of degree of freedom for systems
2	<b>Oscillatory motion</b> - Introduction to oscillatory motion - Simple harmonic motion - Displacement velocity and acceleration relations
3	<b>Free vibration of an undamped single degree of freedom system</b> - Derivation of basic equation - Solving the eq. of motion and finding the natural frequency - Examples
4	<b>Simple energy method (Raleigh principle)</b> - conservative and non-conservative systems - Applying the simple energy method for different systems to find eq. of motion and natural frequency
5	<b>Free vibration of viscous damped single degree of freedom system</b> - Types of damping - Formulation and solving the equation of such system for different damping ratio - Examples
6	<b>Equivalent springs and dampers</b> - Equivalent spring and damping for parallel and series connection - Examples
7	<b>Logarithmic decrement</b> - Formulation of the basic eq. of logarithmic decrement - Calculation the time for the decay of signal - Examples

8	<p><b>Forced vibration of single degree of freedom system</b></p> <ul style="list-style-type: none"> <li>- Formulation of the basic eq. of motion for damped and undamped forced vibration</li> <li>- Behavior of the amplitude with <math>w/\omega_n</math> (eq. of resonance)</li> </ul>
9	<p><b>Forced vibration for constant force</b></p> <ul style="list-style-type: none"> <li>- Behavior of the system with constant excitation force</li> <li>- Formulating the steady state and transient solution</li> <li>- Examples</li> </ul>
10	<p><b>Forced vibration for sinusoidal force (Resonance conditions)</b></p> <ul style="list-style-type: none"> <li>- Behavior of the system with sinusoidal force</li> <li>- Formulation and solution of eq.</li> <li>- Equation for resonance</li> <li>- Examples</li> </ul>
11	<p><b>Rotating unbalance</b></p> <ul style="list-style-type: none"> <li>- Explaining the unbalance forces</li> <li>- Applications and examples</li> </ul>
12	<p><b>Support motion</b></p> <ul style="list-style-type: none"> <li>- Support motion and how this motion affect the motion of the system</li> <li>- Examples</li> </ul>
13	<p><b>Vibration isolation</b></p> <ul style="list-style-type: none"> <li>- Transmissibility</li> <li>- Discussion of transmissibility behavior with <math>w/\omega_n</math> for different damping ratios</li> <li>- Examples</li> </ul>
14	<p><b>Vibration measuring instrument</b></p> <ul style="list-style-type: none"> <li>- The eq. of motion if the measuring device excited by a base force</li> <li>- Amp., Vel., and acceleration that the device measure</li> <li>- Examples</li> </ul>
15  16	<p><b>Two degree of freedom system</b></p> <ul style="list-style-type: none"> <li>- The equations of motion for 2- degree system</li> <li>- Estimating the natural frequency and their mode shap</li> <li>- Coordinate coupling</li> <li>- Semi definite system</li> <li>- Examples</li> </ul>

17	<p><b>Mode shapes</b></p> <ul style="list-style-type: none"> <li>- The mode shapes for different systems of two Degree of freedom</li> <li>- Examples</li> </ul>
18	<p><b>Lagrange equation</b></p> <ul style="list-style-type: none"> <li>- Lagrange ,eq. for damped &amp; undamped system free and forced Vib .</li> <li>- Applying it for several times</li> <li>- Examples</li> </ul>
19	<p><b>Dynamic absorber (undamped)</b></p> <ul style="list-style-type: none"> <li>- formulation of the eq. of dynamic absorber without damping</li> <li>- Examples</li> </ul>
20	<p><b>Damped vibration absorber</b></p> <ul style="list-style-type: none"> <li>- formulation the eq. of dynamic absorber with damping</li> <li>- Examples</li> </ul>
21	<p><b>Multiple degree of freedom system</b></p> <ul style="list-style-type: none"> <li>- Formulating the eq, of motion for multiple degree of freedom systems</li> <li>- Finding the natural freq and their mode shapes</li> </ul>
22	<p><b>Influence coefficient matrix and stiffness matrix</b></p> <ul style="list-style-type: none"> <li>- Finding the eigen values and hence the natural frequencies and the eigen vector ( mode shape ) for multiple degree of freedom systems</li> </ul>
23	<p><b>Wing moment of inertia</b></p> <ul style="list-style-type: none"> <li>- Calculating the wing equivalent moment of inertia</li> <li>- Examples</li> </ul>
24	<p><b>Torsional vibration</b></p> <ul style="list-style-type: none"> <li>- Single degree of freedom systems</li> <li>- Two degree of freedom systems</li> <li>- Multiple degree of freedom systems (using holzer method)</li> <li>- Torsional vibration for stepped shaft</li> <li>- Torsional vibration for shaft with Gears</li> </ul>
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26	

27	<b>Dunkerley's equation for aircraft wing system</b> - Estimating and application of 1 <sup>st</sup> natural frequency for a system of external loads on aircraft wing
28	<b>Rayleigh's equation for aircraft wing</b> - Application of Rayleigh's equation to aircraft wing with lump masses, distributed and combined loads
29	<b>Application of iterative technique for aircraft wing and tail</b> - Estimating the natural frequencies of aircraft wing and tail using the iterative technique from the lowest natural frequency and sweeping matrix
30	- Estimating the highest mode and natural frequencies using the iterative technique and stiffness matrix

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